

HOLDING BRAKE SPECIFICATIONS			
MOMENT OF INERTIA GD <sup>2</sup> /4 (kg·m <sup>2</sup> )	HOLDING TORQUE (N·m)	RATED VOLTAGE	CAPACITY (W)
8.5×10 <sup>-4</sup>	72.6	DC24V 0~+10%	25

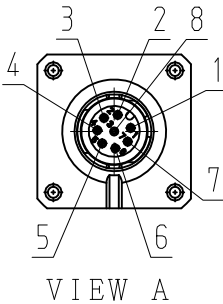
DETAIL OF SHAFT EXTENSION

NOTES.

1. ALL DIMENSIONS ARE IN MILLIMETERS.
2. MOTOR SPECIFICATIONS :900-172-590
3. ENCODER SPECIFICATIONS:900-193-532 (24BIT ABSOLUTE)
4. HOLDING BRAKE CANNOT BE USED TO STOP MOTOR.
5. VIBRATION : 15μm OR BELOW AT RATED SPEED.
6. PLUGS AND CABLE CLAMPS ARE OPTIONAL.
7. READ AND UNDERSTAND DOCUMENT PACKED WITH MOTOR (SAFETY PRECAUTIONS), AND BE CAREFUL USING MOTOR.
8. DEGREES OF PROTECTION:IP67 EXCEPT FOR SHAFT OPENING. MUST USE SPECIFIED CONNECTORS FOR MOTOR.
9. DO NOT TOUCH EACH OF CONNECTOR PINS DIRECTLY. IT CAUSE FAILURE.
10. IN CASE OF MOUNTING THIS MOTOR HORIZONTAL, TO PLACE THE CONNECTOR DOWN IS RECOMMENDABLE.
11. USE HEXAGON SOCKET HEAD CAP SCREWS FOR MOUNTING MOTOR.
12. MOTOR CONNECTOR COULD BE TURNED IN THE RANGE OF ☆ WITHIN 10 TIMES.

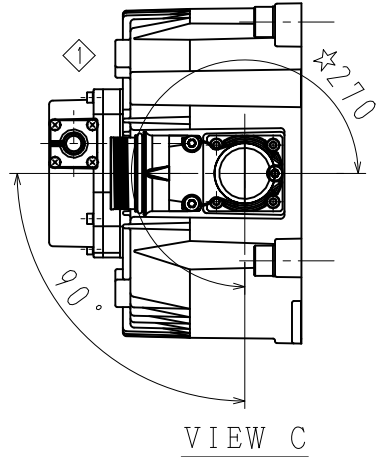
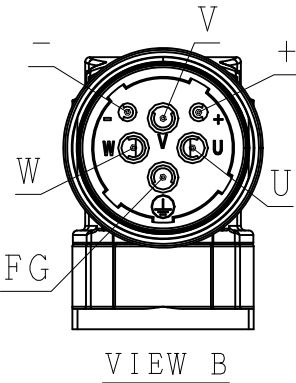
ENCODER TERMINAL CONNECTION

1	PG5V
2	PG0V
3	FRAME GROUND
4	BAT (+)
5	BAT (-)
6	DATA (+)
7	DATA (-)
8	-
CON. CASE	FRAME GROUND



MOTOR TERMINAL CONNECTION

U	PHASE U
V	PHASE V
W	PHASE W
+	BRAKE
-	BRAKE
FG	FRAME GROUND
CON. CASE	FRAME GROUND



RECEPTACLE SIZE:M12

HOUSING:SACC-MSQ-M12MS-25-3, 2 SCO


MAKER:PHOENIX CONTACT

RECEPTACLE SIZE:M40

HOUSING:SM-5EPWN8AAD00S

MAKER:PHOENIX CONTACT

TYPE	RATED OUTPUT kW	RATED TORQUE N·m	TIME RATING	RATED SPEED min <sup>-1</sup>	VOLTAGE V <sub>rms</sub>	RATED CURRENT A <sub>rms</sub>	THERMAL CLASS	WEIGHT kg	ALLOWABLE RADIAL LOAD F <sub>r</sub> N	ALLOWABLE THRUST LOAD F <sub>s</sub> N
SGM7G-55D7F6H	5.5	35	CONT.	1500	400 (3PHASE)	20.8	F	28.0	1764 (AT SHAFT END)	588

F							YASKAWA	DRWN.	H. KATO	TITLE	AC SERVOMOTOR Σ-7 SERIES	DRWN. DATE	Mar. 05' 16	REV.
	2	3	REVISED	FEB. 6, '17	Y. YAMAKAWA/T. HIROSE	SCALE 1 : 4		CHKD.	T. HIROSE		SGM7G MODEL 5.5kW	DWG. NO.	900-191-786	2
	1	2	REVISED	Nov. 25, '16	M. TERADA/T. HIROSE			APRV.	K. AOKI					

SIZE A3