

Direct Drive Servomotors Sigma-7 200 V Series

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Product Overview

SGM7D





Outer Rotor with Core

Ideal for applications that require high torque, high precision and high rigidity.

- High inertia
- Built-in high-resolution (24-bit) encoder
- A high allowable load moment of inertia ratio enables application to large loads
- Large center aperture provides more space for wiring connections

SGM7F





Inner Rotor with Core

SGM7E





Coreless, Inner Rotor

Ideal for applications that require downsizing and a shorter takt time.

- Medium inertia
- Built-in high-resolution (24-bit) encoder
- Compact size with small rotor diameter
- Greater speed and torque stability enable high-speed, high-frequency positioning

Ideal for applications that require smooth movement withput speed fluctuations.

- Low inertia
- Built-in high-resolution (24-bit) encoder
- Smooth operation without speed fluctuations achieved through coreless structure with low cogging

Range Overview

	SGM7D	SGM7F	SGM7E				
Outer diameter of motor (mm)	107 – 264	100 – 360	135 – 290				
Rated torque (Nm)	1.3 - 240	2 – 200	2 – 35				
Maximum torque (Nm)	5 - 400	6 - 600	6 – 105				
Maximum speed (min ⁻¹)	48 - 360	250 - 600	250 – 500				
Supply Voltage	200 V						
Encoder	24 bit (multiturn and incremental)						



Open for challenging Applications

YASKAWA provides equipment for a broad range of applications and offers support in all engineering tasks. This way YASKAWA will find the perfect solution for common tasks and complex automation challenges.

- Quick and easy set-up and no configuration effort these are the benefits of the YASKAWA out-of-the-box solutions.
- In case you want to upgrade a solution, the whole Sigma-7 system can easily be used for any new task.

Complete Solutions

YASKAWA offers comprehensive customized automation solutions with powerful hardware, including controller, visualization, drive concept and industrial robots.

Our motion control products are developed to control all functions in machine process control including motion control, PLC functionality, I/O, sequential logic and process algorithms. Controller integration lowers system cost, increases performance, reduces required panel space and unifies programming.

Process monitoring and diagnostics are inherent features of our platform. These advancements increase product throughput and reduce machine downtime. With our systems in the field, productivity increases by more than 200 % have been achieved. Smoother running and e-stop recovery routines lessen mechanical wear and reduce down time.



For a wide Range of Applications





- Machine tools
- Printing rolls
- Indexers
- Sorters and bonders





- Rotary tables
- Semiconductor manufacturing
- Direct torque transmission
- And many other applications

Sigma-7 Direct Drive Motors Highlights

High precision and performance



Built-in high-resolution 24 bit encoder

With 16.77 million pulses per revolution, we provide the industry-top level of positioning precision.



Improved machine performance

The motion mechanisms stiffness is greatly improved. YASKAWA direct drive motors allow high radial and axial forces. The motors are also available in a high mechanical precision version.

High efficiency and energy saving



Short acceleration and settling time

In combination with the Sigma-7 drive and the performance of the linear motor, the after motion settling time will be shortened significantly.



No gear losses

There is no reduction like a gear or a belt in efficiency due to a power transmitting mechanism, which helps save energy for the machine. A high amount of poles guarantees a smooth running characteristic of the motor. No gear losses.

High reliability and compact design



Ease of operation and high reliability

YASKAWA products stand for high reliability by best performance. YASKAWA Direct Drive Motors are easily handled by the use of the intergrated auto tuning functions.



Direct coupling design and construction

A direct drive servomotor is an actuator that directly transmits the rotational force of the motor so that couplings and other support mechanisms are not required, which saves installation space.

Combination of Direct Drive Servomotors and SERVOPACKs

Direct Drive Servomotor Model		Rated torque	Instantaneous Max. Torque	SERVOPA	ACK Model	
Direct Drive Servon	iotor Model	[Nm]	[Nm]	SGD7S-DDDD		
	SGM7D-30F	30	50			
	SGM7D-58F	58	100			
	SGM7D-90F	90	150	120A*1		
	SGM7D-1AF	110	200			
	SGM7D-01G	1.3	4			
	SGM7D-05G	5	6	2R8A*1, 2R8F*1		
	SGM7D-08G	8	15			
	SGM7D-18G	18	30			
	SGM7D-24G	24	45	120A*1		
	SGM7D-34G	34	60			
	SGM7D-45G	45	75			
	SGM7D-03H	3	4	2R8A*1, 2R8F*1		
	SGM7D-28I	28	50			
	SGM7D-70I	70	100			
SGM7D	SGM7D-1ZI	100	150		-	
(With core, outer rotor)	SGM7D-1CI	130	200			
	SGM7D-2BI	220	300			
	SGM7D-2DI	240	400	120A*1		
	SGM7D-06J	6	8			
	SGM7D-09J	9	15			
	SGM7D-18J	18	30			
	SGM7D-20J	20	45			
	SGM7D-38J	38	60			
	SGM7D-02K	2.06	5			
	SGM7D-06K	6	10			
	SGM7D-08K	8	15	2R8A ^{*1} , 2R8F ^{*1}		
	SGM7D-06L	6	10			
	SGM7D-12L	12	20			
	SGM7D-30L	30	40	120A*1		
	SGM7E-02B	2	6			
	SGM7E-05B	5	15	2R8A, 2R1F		
	SGM7E-07B	7	21			
	SGM7E-04C	4	12		2R8A	
	SGM7E-10C	10	30			
SGM7E (Coreless, inner rotor)	SGM7E-14C	14	42	0004 0005		
	SGM7E-08D	8	24	2R8A, 2R8F		
	SGM7E-17D	17	51			
	SGM7E-25D	25	75			
	SGM7E-16E	16	48		25.4	
	SGM7E-35E	35	105	5F	R5A	
	SGM7F-02A	2	6	0001 0015		
	SGM7F-05A	5	15	2R8A, 2R1F		
	SGM7F-07A	7	21		2R8A	
	SGM7F-04B	4	12	2R8A, 2R8F		
	SGM7F-10B	10	30			
	SGM7F-14B	14	42	5F	R5A	
	SGM7F-08C	8	24	2R8A, 2R8F	2R8A	
	SGM7F-17C	17	51	5F	R5A	
SGM7F (With core, inner rotor)	SGM7F-25C	25	75	7F	R6A	
, ,	SGM7F-16D	16	48	5F	R5A	
	SGM7F-35D	35	105	7R6A ^{*2} , 120A	7R6A*2	
	SGM7F-45M	45	135	7F	R6A	
	SGM7F-80M	80	240	120A		
	SGM7F-1AM	110	330	180A		
	SGM7F-80N	80	240	120A	-	
	SGM7F-1EN	150	450	200A		

*1: An SGM7D Servomotor is used together with an FT-specification SERVOPACK. The following SERVOPACK models can be used.
SGD7S-DDDDDADDF82D
SGD7S-DDDD0ADDF83D
SGD7S-DDD020ADDF84D

*2: Use the derated values given in the table below for the rated output and rated motor speed of this combination.

SGM7D (Outer Rotor, with Core)

digit

Model designations

05

06

80

09

12

18

20

24

28

30

34

38 45

58

70

90

1Z

1A

1C

2B

2D

5.00 Nm

6.00 Nm

8.00 Nm

9.00 Nm

12.0 Nm

18.0 Nm

20.0 Nm

24.0 Nm

28.0 Nm

30.0 Nm

34.0 Nm

38.0 Nm

45.0 Nm

58.0 Nm

70.0 Nm

90.0 Nm

100 Nm

110 Nm

130 Nm

220 Nm

240 Nm

SGN	M7D	-	30	F	7	С	4	1
Direct Dri Servomot			1st + 2nd	3rd	4th	5th	— 6th	_ 7th
1st + 2	2nd digit -	Rate	ed Output		3rd dig	t - Serv	omotor O	uter Diamet
1st + 2 Code	2nd digit - Specifica		· · · ·		3rd dig Code		omotor O ificatio	
		ation	· · · ·			Spec		
Code	Specifica	ation	· · · ·		Code	Spec 264 r	ificatio	

Н	116 mm dia.
1	264 mm dia.
J	150 mm dia.
К	107 mm dia.

L 224 mm x 224 mm

1.

2

Note: Direct Drive Servomotors are not

- available with holding brakes This information is provided to exp-lain model numbers. It is not meant to imply that models are available for all combinations of codes.
- 3 The SGM7D-01G, -05G, and -03H are available only with high mechanical precision.

4th digit - Serial Encoder Code Specification

7*	24-bit multiturn absolute encoder
*	24-bit incremental encoder

Both multiturn absolute encoder and incremental encoder can be used as a single-turn absolute encoder by setting parameters.

5th dig	jit - Design Revision Order
Code	Specification

Standard Version

oth dig	oth ugh - Flange										
Code	ode Mounting		Servomotor Outer Diameter Code (3rd digit)								
Coue	wounting	F	G	Н	1	J	Κ	L			
4	Non-load side with cable on side	\checkmark	\checkmark	\checkmark	-	_	-	\checkmark			
5	Non-load side with cable on bottom	~	√*	-	\checkmark	\checkmark	\checkmark	-			

Applicable models

* SGM7D-01G and -05G are not available with a cable extending from the bottom.

7th digit - Options

Code	Specification
1	Standard mechanical precision
2	High mechanical precision*3

* The SGM7D-01G, -05G, and -03H are available only with high mechanical precision.



More detailed information, technical specifications and accessories (e.g. cables) can be found in our main Sigma-7 200 V catalog. Please contact your YASKAWA representative or find the documents on our website.

SGM7E (Inner Rotor, Coreless)

Model designations

SGN	M7E	-	02	В	7	А	1	1	
Direct Dri Servomot			1st + 2nd	3rd	4th	5th	_ 6th	_ 7th	digit
1st + 2	2nd digit -	Rate	ed Output	t i	3rd dig	it - Serv	omotor O	uter Diam	eter
Code	Specifica	ation			Code	Spec	ificatior	ı	
02	2 Nm				В	135 n	nm dia.		
04	4 Nm				С	175 n	nm dia.		
05	5 Nm				D	230 r	nm dia.		
07	7 Nm				Е	290 r	nm dia.		
08	8 Nm								
10	10 Nm				4th di	git - Se	erial End	coder	
14	14 Nm				Code	Spec	ification	1	
16	16 Nm				7*	24-bi enco		rn absol	ute
17	17 Nm				F*		t increm	ental	
25	25 Nm				F	enco	der		
35	35 Nm							e encode	
						rn absc		be used oder by s	

parameters.

git - Design Revision Order
Specification
Standard version
jit - Flange
Mounting
Non-load side
Non-load side with cable on side
git - Options
Specification
Without options
High machine precision (runout at end of shaft and runout of shaft surface:

Note

1. Direct Drive Servomotors are not available with holding brakes.

2. This information is provided to explain model numbers. It is not meant to imply that models are available for all combinations of codes.



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SGM7F (Inner Rotor, with Core)

Model designations

SGN	Л7F	-	02	А	7	А	1	1	
Direct Driv Servomot			 1st + 2nd	3rd	4th	5th	_ 6th	_ 7th	digit
1st + 2	2nd digit -	Rate	ed Outpu	t	3rd digi	t - Serv	omotor O	uter Diame	eter
Code	Specifica	ation			Code	Spec	ificatior	ı	
Small	Capacity				А	100 n	nm dia.		
02	2 Nm				В	135 n	nm dia.		
04	4 Nm				С	175 n	nm dia.		
05	5 Nm				D	230 r	nm dia.		
07	7 Nm				Μ	280 r	nm dia.		
08	8 Nm				Ν	360 n	nm dia.		
10	10 Nm								
14	14 Nm				4th di	git - Se	erial End	coder	
16	16 Nm				Code	Spec	ification	1	
17	17 Nm				7*			rn absol	ute
25	25 Nm					enco 24-bi	aer t increm	ental	
35	35 Nm				F*	enco		ontai	
Mediu	m Capaci	ty						e encode	
45	45 Nm							be used oder by s	
80	80 Nm				paramete		1010 01100	545. Dy c	.orting

5th dig	5th digit - Design Revision Order					
Code	Specification					
Δ	Standard Version					

6th digit - Flange						
Mounting	Servomotor Outer Diameter Code (3rd digit)					
	Α	В	С	D	M	Ν
Non-load side	\checkmark	\checkmark	\checkmark	\checkmark	—	-
Load side	—	-	-	-	\checkmark	\checkmark
Non-load side	—	_	_	_	\checkmark	\checkmark
Non-load side (with cable on side)	\checkmark	\checkmark	\checkmark	\checkmark	-	_
	Mounting Non-load side Load side Non-load side Non-load side (with	Mounting Servon Non-load side ✓ Load side — Non-load side — Non-load side — Non-load side —	Mounting Servemotor Outer Non-load side ✓ Load side ✓ Non-load side — Non-load side — Non-load side —	Servomotor Outer Dian A B C Non-load side ✓ ✓ ✓ Load side — — — Non-load side — — — Non-load side — — — Non-load side — — —	Servomotor Outer Diameter Co Mounting A B C D Non-load side ✓ ✓ ✓ ✓ ✓ Load side — — — — — — Non-load side — — — — — — — Non-load side (with ✓ ✓ ✓ ✓ ✓ ✓	Servomotor Outer Diameter Code (3rd) A B C D M Non-load side ✓

Applicable models

7th	diait	- 0	ptions
	aigit	<u> </u>	priorito

2

Code	Specification
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Without Options 1

High machine precision (runout at end of

shaft and runout of shaft surface: 0.01 mm)

Note

1A

1E

2Z

110 Nm

150 Nm

200 Nm

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2. This information is provided to explain ordel numbers. It is not meant to imply that models are available for all combinations of codes



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